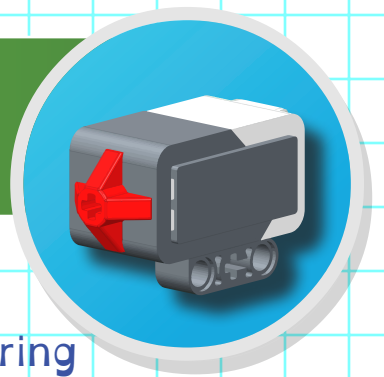
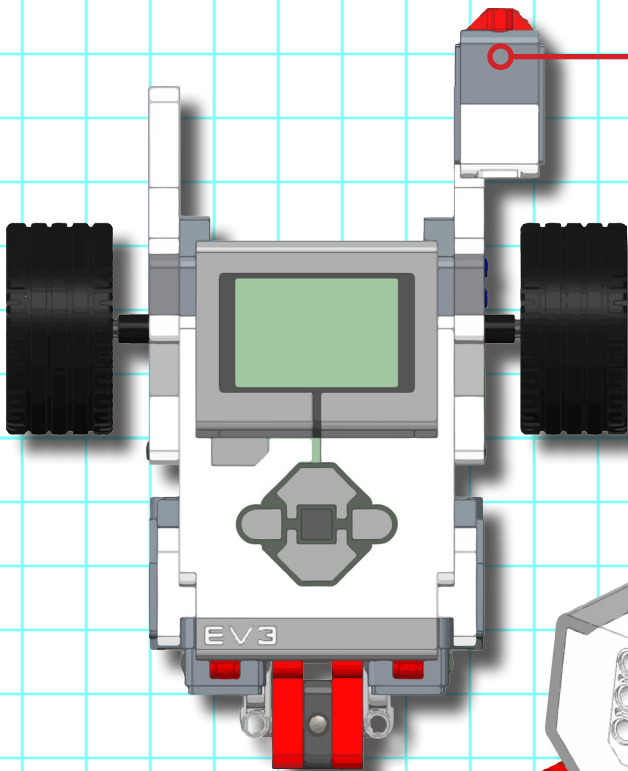


Building Tips

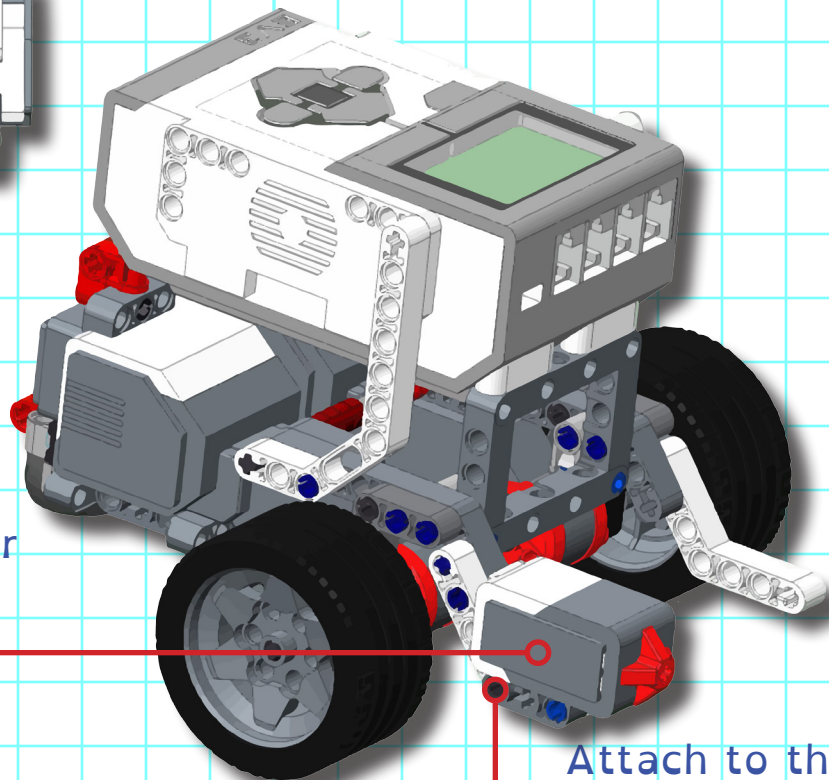


Touch Sensor Attachment

The touch sensor is useful for triggering different behaviors. It can be used to make the robot change directions or activate the medium motor.



Make sure the sensor sticks out from robot so it is the first thing to touch an object in front of it



Position the sensor at the height of the object you want to touch

Attach to the robot in two or more places for strength